

## CC-100-1000

Converter for driving permanent-magnet synchronous motors (PMSM) and brushless DC motors (BLDC).

- Sensorless speed control from 5,000 rpm up to 500,000 rpm
- Maximum output power of 1,000 W
- No output filter required
- Separate supply for power and digital part
- User definable setup for different motor parameters
- Torque or speed control
- Integrated braking chopper up to 2 W
- Optional external braking chopper up to 420 W
- Highest possible efficiency
- Parallel connection of several converters to one DC-Bus possible
- User-friendly PC control software (CelerotonPilot)



Specifications converter	
Input voltage power part U <sub>in</sub> (DC)	24 – 100 V
Input voltage digital part U <sub>in</sub> (DC)	24 V
Maximum output power (with respective cooling)	1,000 W
Output voltage (peak value phase-phase)	0 – 0.93 U <sub>in</sub>
Maximum phase current (PAM-operation)	8.7 Arms/12.3 Apeak <sup>1</sup>
Maximum frequency/speed (PAM-operation)	8.3 kHz/500,000 rpm
Operating range	4-Quadrant
Communication interface	USB
Communication interfaces (optional)	RS232, CAN
PC control software	CelerotonPilot
Weight	0.28 kg
Dimensions (L x W x H) without heat sink	195 x 125 x 24 mm
Dimensions (L x W x H) with heat sink	195 x 125 x 62.62 mm
Operating temperature	0 – 40 °C

### User interface (X7, X8)

Connector X7 – I/O Interface (8 pins)		
2 x Digital inputs	0 – 4 V Low Le 10 – 24 V High Le	
3 x Digital outputs	0 – 24 V (Relay, normally open contacts)	
1 x COM	Common rail for digital outputs	
2 x GND		

<sup>&</sup>lt;sup>1</sup> Fundamental of the PAM block current



Connector X8 – I/O Interface (6 pins)		
1 x Analog input	0 – 10 V	
1 x Analog output	0 – 10 V	
1 x Temperature measurement input	PTC or NTC, resistance range according to option Tx	
1 x Auxiliary power supply	10 V, 200 mA	
2 x GND		

# **Operating range**

The operating range of the converter is dependent on the output voltage ( $U_{out}$ ) (peak value phase-phase) in Figure 1. The output power ( $P_{out}$ ) increases with the output voltage as the phase current ( $i_{ph}$ ) (rms) is constant until the power limit is reached. Above that point  $i_{ph}$  decreases with increasing output voltage. The input voltage ( $U_{in}$ ) (grey area) must be higher than the maximum required output voltage.

Operating with full output power of 1,000 W requires cooling with heat sink with thermal resistance  $R_{th} \le 1$  K/W. Without heat sink a maximum phase current of 2.3 A and maximum output power of 280 W is available.

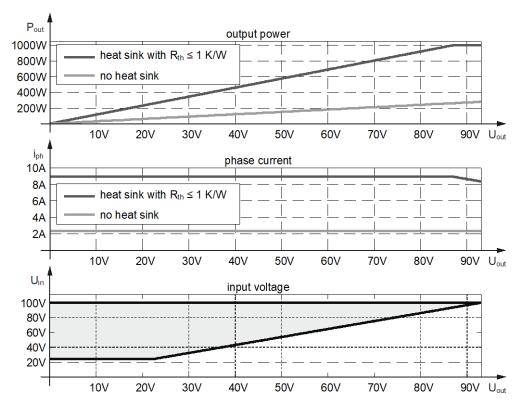


Figure 1: Output power, phase current and input voltage range of the converter CC-100-1000.



## Order codes: CC-100-1000.SLx.Tx.HS

Sensorless SLx	
SL1 (Standard)	Speed constants between 550 and 18,250 rpm/V
	Sensorless speed control from 7,000 rpm
SL2	Speed constants between 400 and 7,900 rpm/V
	Sensorless speed control from 5,000 rpm

The stated values are valid for number of pole pairs p=1. For higher number of pole pairs the speed constants and minimum speeds are divided by the number of pole pairs p.

PTC/NTC Tx	
T1 (Standard)	Measurement range 6-150 $\Omega$ , e.g. PT100
T2	Measurement range 0.26-86 k $\Omega$ , e.g. KTY84, NTC10k

Heat sink HS	
_ (Standard)	Without heat sink
HS	With heat sink

# **Accessories**

Connector set CC-100-1000

Ordering information	Article number
CC-100-1000.SL1.T1	A4030063
CC-100-1000.SL1.T2	A4030064
CC-100-1000.SL2.T1	A4030065
CC-100-1000.SL2.T2	A4030066
CC-100-1000.SL1.T1.HS	A4030067
CC-100-1000.SL1.T2.HS	A4030068
CC-100-1000.SL2.T1.HS	A4030069
CC-100-1000.SL2.T2.HS	A4030070
Connector set CC-100-1000	A4080031



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