

CC-75-500

Converter for driving permanent-magnet synchronous motors (PMSM) and brushless DC motors (BLDC).

- Sensorless speed control from 0 rpm to 1 Million rpm
- Maximum output power of 500 W (800 W resp.)
- No output filter required
- User definable setup for different motor parameters
- Customer-definable input and output connections
- Torque or speed control
- Internal or external braking chopper
- Highest possible efficiency
- Mountable on a DIN-rail
- Parallel connection of several converters to one DC-Bus possible
- User-friendly PC control software (CelerotonPilot)



| Specifications converter | |
|---|--|
| Input voltage U _{in} (DC) | 24 – 75 V |
| Maximum output power | 500 W (800 W with HC-option) |
| Output voltage (peak value phase-phase) | 0 – 0.95 U _{in} |
| Maximum phase current (PAM-operation) | 6.2 Arms/8.8 Apeak ¹ |
| | (10.9 Arms/15.4 Apeak¹ with HC-option) |
| Maximum frequency/speed (PAM-operation) | 16.6 kHz/1,000,000 rpm |
| Operating range | 4-Quadrant |
| Communication interface | USB |
| Optional communication interfaces | RS232, RS485, CAN |
| Communication interface upon request | Ethernet |
| PC control software | CelerotonPilot |
| Weight | 1 kg |
| Dimensions | 215 x 135 x 35 mm |
| Operating temperature | 0 – 40 °C |

¹ Fundamental of the PAM block current

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User interface (X2, X3, X4)

Standard configuration E01

| Connector X2 – Motor Interface (8 pins) | |
|---|---|
| 1 x GND | |
| 3 x Digital hall sensor inputs | (open collector), pull up to 5 V |
| 1 x Power supply | 5 V, 100 mA |
| 1 x Temperature measurement input | PTC or NTC, resistance range according to option Tx |
| 1 x Temperature measurement input | Thermocouple type K |
| 1 x Analog GND | |

| Connector X3 – Digital Interface (8 pins) | |
|---|--|
| 1 x GND | |
| 1 x Digital GND | Digital GND for digital inputs |
| 2 x Digital inputs | 0 – 24 V, galvanically isolated (software adjustable thresholds 0.8 – 20 V) |
| 1 x COM | Common rail for digital outputs |
| 2 x Digital outputs | 0 – 24 V (Relay, normally open contacts) |
| 1 x Auxiliary power supply | 12 – 24 V (adjustable), 200 mA (max.) e.g. for digital inputs/outputs |

| Connector X4 – Analog Interface (6 pins) | |
|--|--------------|
| 1 x Analog GND | |
| 2 x Analog inputs | 0 – 10 V |
| 2 x Analog outputs | 0 – 10 V |
| 1 x Power supply | 10 V, 100 mA |

Connectors X2, X3 and X4 can be customized according to user specifications.



Operating range

The operating range of the converter is dependent on the output voltage (U_{out}) (peak value phase-phase) in Figure 1. The output power (P_{out}) increases with the output voltage as the phase current (i_{ph}) is constant until the power limit is reached. Above that point i_{ph} decreases with increasing output voltage. The input voltage (U_{in}) (grey area) must be higher than the maximum required output voltage.

The maximum output power (P_{out}) of the converter CC-75-500 depends on the ambient temperature (T_{amb}). The average power losses in the breaking chopper ($P_{chopper}$) are limited by the output power and the ambient temperature. The respective relation is depicted in Figure 2.

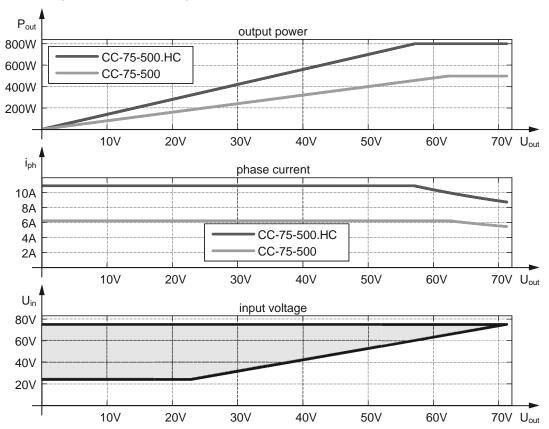


Figure 1: Output power, phase currents and input voltage range of the converters CC-75-500 and CC-75-500.HC.

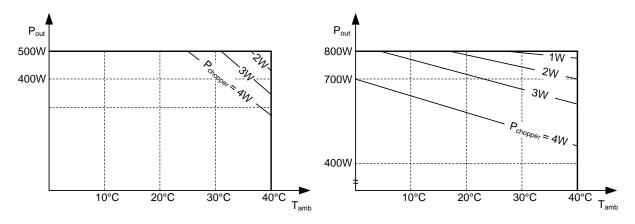


Figure 2: Safe operating areas (SOA) of the converter CC-75-500 (left) and CC-75-500.HC (right) versus ambient temperature (T_{amb}) and the allowed average power losses in the breaking chopper ($P_{chopper}$).



Order codes: CC-75-500.HC.Exx.SLx.CO1.Tx

| High current HC | | |
|--|--|--|
| НС | Version with 800 W output power | |
| | | |
| Extension Board Exx (Configuration of the connectors X2, X3, X4) | | |
| E01 (standard) | Standard – see page 2 Standard configuration E01 | |
| | | |
| Sensorless SLx | | |
| SL1 (standard) | Speed constants between 550 and 18,250 rpm/V | |
| | Sensorless speed control from 7,000 rpm | |
| SL2 | Speed constants between 400 and 7,900 rpm/V | |
| | Sensorless speed control from 5,000 rpm | |

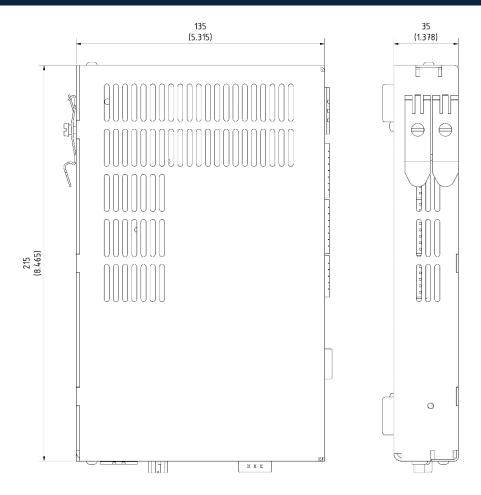
The stated values are valid for number of pole pairs p=1. For higher number of pole pairs the speed constants and minimum speeds are divided by the number of pole pairs p.

| Communication interfaces CO1 | | | | |
|------------------------------|-----|--------------------------------|---|--|
| | USB | CAN | RS232/RS485 | |
| CO1 (standard) | X | X | X | |
| | | | | |
| PTC/NTC Tx | | | | |
| T1 (standard) | | Measurement range 6 | Measurement range 6 – 150 Ω , e.g. PT100 | |
| Т2 | | Measurement range 0. NTC10k | Measurement range 0.26 – 86 k Ω , e.g. KTY84, NTC10k | |

| Ordering information | Article number |
|-----------------------------|----------------|
| CC-75-500.E01.SL1.CO1.T1 | A4030015 |
| CC-75-500.E01.SL1.CO1.T2 | A4030016 |
| CC-75-500.E01.SL2.CO1.T1 | A4030027 |
| CC-75-500.E01.SL2.CO1.T2 | A4030028 |
| CC-75-500.HC.E01.SL1.CO1.T1 | A4030039 |
| CC-75-500.HC.E01.SL1.CO1.T2 | A4030040 |
| CC-75-500.HC.E01.SL2.CO1.T1 | A4030051 |
| CC-75-500.HC.E01.SL2.CO1.T2 | A4030052 |
| Connector set CC-75-500 | A4080030 |



Drawing in mm [inch]



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